

A

B

Q. No.	Key	Answer	Q. No.	Key	Answer
1.	a	1	1.	a	$7 / \sqrt{30}$
2.	a	$k^3 \det(A)$	2.	a	1
3.	c	Infinitely many solution	3.	b	8
4.	a	is always consistent	4.	a	is always consistent
5.	d	$\theta = 2\pi/3$	5.	a	$k^3 \det(A)$
6.	b	\vec{a} is perpendicular to \vec{b}	6.	d	$\theta = 2\pi/3$
7.	b	8	7.	c	Infinitely many solution
8.	b	(-8, -6, -22)	8.	b	\vec{a} is perpendicular to \vec{b}
9.	a	$7 / \sqrt{30}$	9.	b	(-8, -6, -22)
10.	c	$ \vec{r} = \vec{a} $	10.	a	$\cos x$
11.	c	-1	11.	c	-1
12.	a	purely imaginary	12.	b	minimum value at $x=0$
13.	c	-16	13.	a	purely imaginary
14.	d	Arguments of the product of two complex numbers is equal to sum of their arguments	14.	a	3
15.	d	a hyperbola	15.	d	Arguments of the product of two complex numbers is equal to sum of their arguments
16.	c	8	16.	c	8
17.	a	(4, 4), (-4, -4)	17.	b	$y - 5 = 0$
18.	b	$y - 5 = 0$	18.	d	a hyperbola
19.	a	3	19.	a	$-\cot \theta$
20.	a	$-\cot \theta$	20.	c	-16
21.	b	0	21.	b	0
22.	b	minimum value at $x=0$	22.	c	$ \vec{r} = \vec{a} $
23.	b	an asymptote parallel to y-axis	23.	b	an asymptote parallel to y-axis
24.	a	$\cos x$	24.	a	(4, 4), (-4, -4)
25.	d	$3\pi / 8$	25.	d	$3\pi / 8$
26.	a	3/2	26.	a	4
27.	a	48	27.	a	3 / 2
28.	a	$f(2a - x) = f(x)$	28.	a	$f(2a - x) = f(x)$
29.	b	$\frac{d^2y}{dx^2} = 0$	29.	a	48
30.	b	$ydx - xdy = 0$	30.	b	$ydx - xdy = 0$
31.	a	$x dv + (2v + v^2) dx = 0$	31.	b	$\frac{d^2y}{dx^2} = 0$
32.	b	2, 1	32.	b	24 / 169
33.	c	(Z, .)	33.	a	$x dv + (2v + v^2) dx = 0$
34.	c	$\sim p \vee q$	34.	c	(Z, .)
35.	b	1	35.	b	1
36.	d	[2]	36.	d	[2]
37.	b	$\frac{24}{169}$	37.	d	np, npq
38.	a	4	38.	c	$\sim p \vee q$
39.	d	$\frac{1}{5\sqrt{2\pi}}$	39.	d	$\frac{1}{5\sqrt{2\pi}}$
40.	d	np, npq	40.	b	2, 1

SECTION - B

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$$41. \begin{bmatrix} 1 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 8 \end{bmatrix}$$

- 1 mark

$$|A| = \begin{vmatrix} 1 & 1 \\ 2 & 3 \end{vmatrix} = 1 \neq 0$$

- 1 mark

$$A^{-1} = \begin{bmatrix} 3 & -1 \\ -2 & 1 \end{bmatrix}$$

- 2 marks

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 & -1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 8 \end{bmatrix}$$

- 1 mark

$$x = 1, y = 2$$

- 1 mark

$$45. A \sim \begin{bmatrix} 1 & -2 & 3 & 4 \\ 0 & 0 & 5 & 5 \\ 0 & 0 & 10 & 10 \end{bmatrix} \begin{array}{l} R_2 \leftrightarrow R_2 + 2R_1 \\ R_3 \leftrightarrow R_3 + R_1 \end{array}$$

- 3 marks

$$\sim \begin{bmatrix} 1 & -2 & 3 & 4 \\ 0 & 0 & 5 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{l} R_3 \rightarrow R_3 - 2R_2 \end{array}$$

- 2 marks

$$\therefore \rho(A) = 2$$

- 1 mark

$$43. (i) \vec{r} = -\vec{i} - \vec{k}$$

- 1 mark

$$\vec{M} = \vec{r} \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -1 & 0 & -1 \\ 3 & 2 & -4 \end{vmatrix}$$

- 1 mark

$$= 2\vec{i} - 7\vec{j} - 2\vec{k}$$

- 1 mark

$$(ii) [\vec{a} \ \vec{b} \ \vec{c}] = \begin{vmatrix} 3 & 2 & -4 \\ 9 & 8 & -10 \\ \lambda & 4 & -6 \end{vmatrix} = 0$$

- 2 marks

$$\Rightarrow \lambda = 5$$

- 1 mark

$$44. [\vec{a} \times \vec{b}, \vec{b} \times \vec{c}, \vec{c} \times \vec{a}] = \{(\vec{a} \times \vec{b}) \times (\vec{b} \times \vec{c})\} \cdot (\vec{c} \times \vec{a})$$

- 1 mark

$$= \{[\vec{a} \ \vec{b} \ \vec{c}] \vec{b} - [\vec{a} \ \vec{b} \ \vec{b}] \vec{c}\} \cdot (\vec{c} \times \vec{a})$$

- 2 marks

$$= [\vec{a} \ \vec{b} \ \vec{c}] \{ \vec{b} \cdot (\vec{c} \times \vec{a}) \}$$

- 1 mark

$$= [\vec{a} \ \vec{b} \ \vec{c}] [\vec{a} \ \vec{b} \ \vec{c}]$$

- 1 mark

$$= [\vec{a} \ \vec{b} \ \vec{c}]^2$$

- 1 mark

Note : Different method can be adopted

45. $\sqrt{-8 - 6i} = x + iy$ - 1 mark
 $x^2 - y^2 = -8$ and $2xy = -6$ mathstimes.com
 $x = \pm 1$ - 2 marks
 $y = \pm 3$ - 1 mark
 Ans (1 - 3i) or (-1 + 3i) - 1 mark
 Note : Different method can be adopted

46. $z_1 = r_1 (\cos \theta_1 + i \sin \theta_1)$ and $z_2 = r_2 (\cos \theta_2 + i \sin \theta_2)$ - 1 mark
 $|z_1| = r_1, \arg z_1 = \theta_1; |z_2| = r_2, \arg z_2 = \theta_2$ - 1 mark
 $z_1 \cdot z_2 = r_1 r_2 [\cos (\theta_1 + \theta_2) + i \sin (\theta_1 + \theta_2)]$ - 2 marks
 $\therefore |z_1 z_2| = r_1 r_2 = |z_1| \cdot |z_2|$ and - 1 mark
 $\arg (z_1 z_2) = \theta_1 + \theta_2 = \arg z_1 + \arg z_2$ - 1 mark

47. Combined equation of asymptotes is $3x^2 - 5xy - 2y^2 + 17x + y + k = 0$ - 1 mark
 \therefore Separate equations are $x - 2y + 1 = 0, 3x + y + m = 0$ - 2 marks
 $m_1 = 1/2, m_2 = -3$ - 1 mark
 Angle between the lines is $\tan \theta = 7$ - 1 mark
 $\theta = \tan^{-1} (7)$ - 1 mark
 Another method :
 $\tan \theta = \left| \frac{2\sqrt{h^2 - ab}}{a + b} \right|$ - 2 marks
 we have $a = 3, b = -2, 2h = -5$ - 2 marks
 $\tan \theta = 7$ - 1 mark
 $\theta = \tan^{-1} (7)$ - 1 mark

48. $f(0) = 1$ - 1 mark
 $f'(0) = -1$ - 1 mark
 $f''(0) = 2$ - 1 mark
 $f(x) = f(0) + \frac{x}{1!} f'(0) + \frac{x^2}{2!} f''(0) + \dots$ - 1 mark
 $\frac{1}{1+x} = 1 - x + x^2 - \dots$ - 2 marks
 Note : The sign of the 4th term may be put as + or -

49. $\frac{\delta u}{\delta x} = \frac{\sec^2 x}{\tan x + \tan y + \tan z}$ - 2 marks
 $\sin 2x \frac{\delta u}{\delta x} = \frac{2 \tan x}{\tan x + \tan y + \tan z}$ - 1 mark
 $\sin 2y \frac{\delta u}{\delta y} = \frac{2 \tan y}{\tan x + \tan y + \tan z}$ - 1 mark
 $\sin 2z \frac{\delta u}{\delta z} = \frac{2 \tan z}{\tan x + \tan y + \tan z}$ - 1 mark
 $\Sigma \sin 2x \frac{\delta u}{\delta x} = 2$ - 1 mark

50. $I = \int_{\pi/6}^{\pi/3} \frac{dx}{1 + \sqrt{\tan(\frac{\pi}{2} - x)}}$ mathstimes.com
- 1 mark

$I = \int_{\pi/6}^{\pi/3} \frac{dx}{1 + \sqrt{\cot x}}$ - 1 mark

$2I = \int_{\pi/6}^{\pi/3} dx$ - 2 marks

$= \frac{\pi}{6}$ - 1 mark

$I = \frac{\pi}{12}$ - 1 mark

51. (i) The characteristic equation is $p^2 + 6p + 9 = 0$
- $(p + 3)^2 = 0 \Rightarrow p = -3, -3$ - 1 mark
- The C.F is $(Ax + B)e^{-3x}$ - 1 mark
- The general solution is $y = (Ax + B)e^{-3x}$ - 1 mark
- (ii) First differentiation - 1 mark
- Second differentiation - 1 mark
- $y'' - 4y' + 4y = 0$ is the required differential equation - 1 mark

52.

p	q	r	$p \wedge q$	$(p \wedge q) \vee r$
T	T	T	T	T
T	T	F	T	T
T	F	T	F	T
T	F	F	F	F
F	T	T	F	T
F	T	F	F	F
F	F	T	F	T
F	F	F	F	F

Column 1 to 4 (each 1 mark) - 4 marks

Column 5 - 2 marks

Note : The order of the rows need not be same as in the scheme.

52. $E(x) = \frac{1}{3}$ - 2 marks

$E(x^2) = \frac{2}{9}$ - 2 marks

$\text{Var}(x) = \frac{1}{9}$ - 2 marks

54. $f(x) = ke^{-2(x^2 - 2x + 1)}$ - 1 mark
 $= k e^{-2(x-1)^2}$ mathstimes.com
 $= k \cdot e^{-\frac{1}{2}} \left(\frac{x-1}{1/2}\right)^2$ - 1 mark
 $\sigma = \frac{1}{2}, m = 1$ - 2 marks
 $k = \sqrt{\frac{2}{\pi}}$ - 1 mark

55. (a) Point $(x, y) = (0, 1)$ - 1 mark
 $m_1 = \log a$ - 1 mark
 $m_2 = \log b$ - 1 mark
 If θ be the angle between them then
 $\tan \theta = \left| \frac{m_1 - m_2}{1 + m_1 m_2} \right|$ - 1 mark
 $\theta = \tan^{-1} \left[\left| \frac{\log a - \log b}{1 + \log a \log b} \right| \right]$ - 2 marks

55. (b) Stating - 1 mark
 $a * b = a * c \Rightarrow b = c$ - 1 mark
 $b * a = c * a \Rightarrow b = c$
 Proving
 $a * b = a * c \Rightarrow b = c$ - 2 marks
 $b * a = c * a \Rightarrow b = c$ - 2 marks
 Note : For LCL the left elements must be same. For RCL the right elements must be same. One may take any three different elements.

SECTION - C

56. $[A, B] = \begin{bmatrix} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & \lambda & \mu \end{bmatrix}$ - 2 marks
 $\sim \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & \lambda - 3 & \mu - 10 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - R_2 \end{array}$ - 2 marks

Case (i) $\lambda = 3$ and $\mu \neq 10, \therefore \rho(A) \neq \rho[A, B]$
 \therefore the given system is inconsistent and has no solution - 2 marks
 Case (ii) $\lambda \neq 3$, and $\mu \neq 10, \rho(A) = \rho[A, B] = 3 =$ number of unknowns
 \therefore the given system is consistent and has a unique solution - 2 marks
 Case (iii) $\lambda = 3$ and $\mu = 10, \rho(A) = \rho[A, B] = 2 <$ number of unknowns
 \therefore the given system is consistent but has an infinite number of solutions - 2 marks

57. Rough diagram

$$\vec{OP} = \cos A \vec{i} + \sin A \vec{j}$$

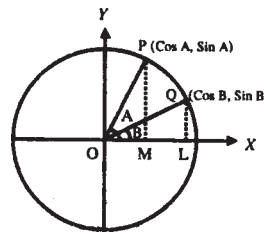
$$\vec{OQ} = \cos B \vec{i} + \sin B \vec{j}$$

$$\vec{OP} \cdot \vec{OQ} = \cos A \cos B + \sin A \sin B$$

$$\vec{OP} \cdot \vec{OQ} = \cos(A - B)$$

$$\cos(A - B) = \cos A \cos B + \sin A \sin B$$

Note : Instead of P and Q they can use any letters



- 3 marks
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- 2 marks

- 2 marks

- 1 mark

- 1 mark

- 1 mark

58. $\vec{a} = -\vec{i} + \vec{j} + \vec{k}$

$$\vec{b} = \vec{i} - \vec{j} + \vec{k}$$

$$\vec{v} = \vec{i} + 2\vec{j} + 2\vec{k}$$

Vector Form

$$\vec{r} = (1 - s)(-\vec{i} + \vec{j} + \vec{k}) + s(\vec{i} - \vec{j} + \vec{k}) + t(\vec{i} + 2\vec{j} + 2\vec{k})$$

$$\text{(OR)} \quad \vec{r} = (-\vec{i} + \vec{j} + \vec{k}) + s(2\vec{i} - 2\vec{j}) + t(\vec{i} + 2\vec{j} + 2\vec{k})$$

Cartesian Form :

$$\begin{vmatrix} x+1 & y-1 & z-1 \\ 2 & -2 & 0 \\ 1 & 2 & 2 \end{vmatrix}$$

$$-4x - 4y + 6z - 6 = 0$$

(OR)

$$2x + 2y - 3z + 3 = 0$$

- 2 marks

- 3 marks

- 3 marks

- 2 marks

59. $x = 1 \pm i\sqrt{3}$

$$\alpha^n = 2^n \left(\cos n \frac{\pi}{3} + i \sin n \frac{\pi}{3} \right)$$

$$\beta^n = 2^n \left(\cos n \frac{\pi}{3} - i \sin n \frac{\pi}{3} \right)$$

$$\alpha^n - \beta^n = i 2^{n+1} \sin n \frac{\pi}{3}$$

$$\alpha^9 - \beta^9 = 0$$

- 2 marks

- 2 marks

- 2 marks

- 2 marks

- 2 marks

60. Diagram

$$x^2 = 4ay$$

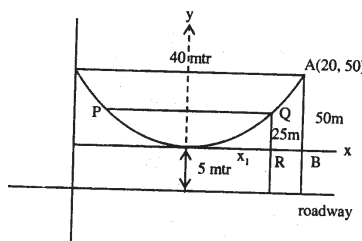
$$\therefore a = 2$$

$$x^2 = 8y$$

The point Q is $(x_1, 25)$ lies on the parabola

$$\Rightarrow x_1 = 10\sqrt{2}$$

$$PQ = 2x_1 = 20\sqrt{2} \text{ mts}$$



- 3 marks

- 1 mark

- 2 marks

- 1 mark

- 1 mark

- 1 mark

- 1 mark

61. Diagram

$$\frac{(x-1)^2}{25} + \frac{(y-2)^2}{9} = 1$$

$$e = \frac{4}{5}$$

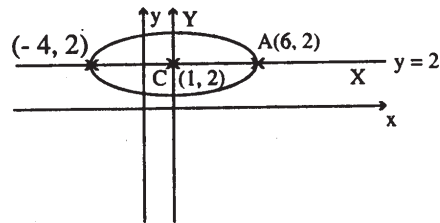
centre C (1, 2)

Foci $F_1(5, 2)$

$F_2(-3, 2)$

Vertices A(6, 2)

A'(-4, 2)



- 2 marks
 mathstimes.com
 - 2 marks

- 1 mark

- 1 mark

- 1 mark

- 1 mark

- 1 mark

- 1 mark

Note : Only a rough diagram is enough with indication of proper type

62. Other asymptote is $2x - y + k = 0$

Equation of RH is $(x + 2y - 5)(2x - y + k) + c = 0$

Passing through (6, 0)

$$k + c = -12$$

Passing through (-3, 0)

$$-8k + C = -48$$

$$k = 4, c = -16$$

Equation of RH is

$$(x + 2y - 5)(2x - y + 4) - 16 = 0$$

Note : One may take the unknown k, c in a different manner. Further the last stage need not be simplified.

- 1 mark

- 2 marks

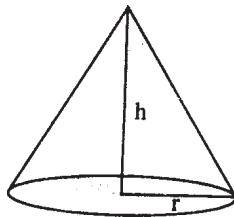
- 2 marks

- 2 marks

- 2 marks

- 1 mark

63. Diagram



$$\frac{dV}{dt} = 30 \text{ ft}^3 / \text{min}$$

$$\text{Volume of cone } V = \frac{1}{3} \pi r^2 h$$

$$V = \frac{\pi}{12} (h^3)$$

$$\frac{dV}{dt} = \frac{\pi}{12} \times 3h^2 \frac{dh}{dt}$$

\therefore the height of the cone is increased at the rate of $\frac{6}{5\pi}$ ft/min

- 1 mark

- 1 mark

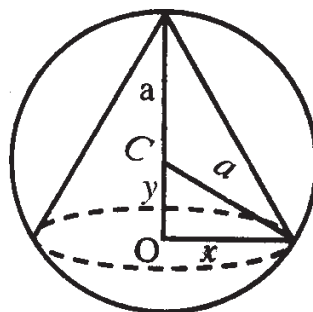
- 1 mark

- 2 marks

- 2 marks

- 3 marks

64. Rough diagram



- 2 marks

Volume of the cone

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$$V = \frac{1}{3} \pi x^2 (a + y)$$

- 1 mark

$$= \frac{1}{3} \pi (a^2 - y^2) (a + y)$$

- 1 mark

$$V' = 0 \Rightarrow y = \frac{a}{3}$$

- 3 marks

When $y = \frac{a}{3}$, $V'' < 0$

- 2 marks

$$V = \frac{8}{27} \text{ (Volume of the sphere)}$$

- 1 mark

Note : This problem can be done by different method also. If the method is correct full credit should be given

65. $f = \tan u$

- 2 marks

degree of $f = 2$

- 2 marks

$$x \frac{\delta f}{\delta x} + y \frac{\delta f}{\delta y} = 2f$$

- 3 marks

$$x \sec^2 u \frac{\delta u}{\delta x} + y \sec^2 u \frac{\delta u}{\delta y} = 2 \tan u$$

- 2 marks

$$x \frac{\delta u}{\delta x} + y \frac{\delta u}{\delta y} = \sin 2u$$

- 1 mark

66. Diagram

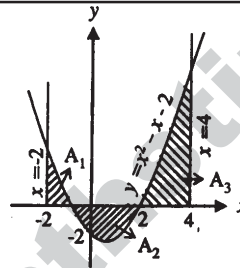
- 3 marks

This curve intersects x axis

at $x = -1$ and $x = 2$

- 1 mark

$$= \int_{-2}^{-1} y dx + \int_{-1}^{2} (-y) dx + \int_{2}^{4} y dx \text{ (or)}$$



$$= \int_{-2}^{-1} (x^2 - x - 2) dx + \int_{-1}^{2} -(x^2 - x - 2) dx + \int_{2}^{4} (x^2 - x - 2) dx$$

- 3 marks

= 15 sq units

- 3 marks

67. Rough Diagram

- 1 mark

$$x^2 + y^2 = a^2$$

$x = 0$ and $x = a$

- 1 mark

$$\text{Perimeter} = 4 \int_0^a \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

- 2 marks

$$\frac{dy}{dx} = \frac{-x}{y}$$

- 1 mark

$$\sqrt{1 + \left(\frac{dy}{dx}\right)^2} = \frac{a}{y} = \frac{a}{\sqrt{a^2 - x^2}}$$

- 1 mark

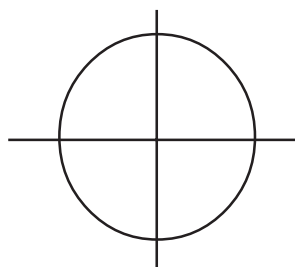
$$\text{Perimeter} = 4 \int_0^a \frac{a}{\sqrt{a^2 - x^2}} dx$$

- 2 marks

= $2\pi a$

- 2 marks

Note : Different method can be adopted.



68. $P^2 - 1 = 0$ - 1 mark
 $p = \pm 1$ mathstimes.com
 $CF = Ae^x + Be^{-x}$ - 1 mark
 $PI_1 = -\frac{1}{5} \cos 2x$ - 3 marks
 $PI_2 = \frac{2}{5} \sin 2x$ (OR) $-\frac{2}{5} \sin 2x$ - 2 marks
 $y = Ae^x + Be^{-x} - \frac{1}{5} \cos 2x + \frac{2}{5} \sin 2x$ - 2 marks
- 1 mark

69. $\frac{dA}{dt} \propto A$ - 1 mark
 $\frac{dA}{dt} = KA$ - 1 mark
 $\Rightarrow \frac{dA}{dt} = 0.04t$ - 1 mark
 $A = Ce^{0.04t}$ - 2 marks
when $t = 0, c = 1000$ - 1 mark
when $A = 2000,$
 $2000 = 1000 e^{0.04t}$ - 2 marks
 $t = 17$ years (app...) - 2 marks

70.a (i) **Closure axiom**

$$A = \begin{pmatrix} x & x \\ x & x \end{pmatrix} \in G, B = \begin{pmatrix} y & y \\ y & y \end{pmatrix} \in G$$

$$AB = \begin{pmatrix} 2xy & 2xy \\ 2xy & 2xy \end{pmatrix} \in G$$
 - 2 marks

(ii) **Associative axiom**

Matrix multiplication is always associative - 1 mark

(iii) **Identity axiom**

$$E = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} \in G$$
 - 3 marks

(iv) **Inverse axiom**

$$A^{-1} = \begin{pmatrix} \frac{1}{4x} & \frac{1}{4x} \\ \frac{1}{4x} & \frac{1}{4x} \end{pmatrix} \in G$$
 - 3 marks

G is a group under matrix multiplication - 1 mark

70. b $K = \frac{1}{49}$ - 2 marks

$$P(x < 4) = \frac{16}{49}$$
 - 2 marks

$$P(x \geq 5) = \frac{24}{49}$$
 - 2 marks

$$P(3 < x \leq 6) = \frac{33}{49}$$
 - 2 marks

\therefore the smallest value of x for which

$$P(X \leq x) > \frac{1}{2} \text{ is } 4$$
 - 2 marks