



**MODEL HIGHER SECONDARY
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KEY FOR MATHEMATICS

A

B

Q No.	Option	Answer	Q No.	Option	Answer
1.	2	4	1.	2	$(-8, -6, -22)$
2.	4	inverse axiom	2.	3	2
3.	3	ω^{n-k}	3.	2	$\sqrt{3}\lambda$
4.	4	taking finite number of elementary transformations	4.	1	$(2, -1, 4)$ and 5
5.	2	$\frac{1}{50\pi} \text{ cm/min}$	5.	1	$\pi \int_c^d x^2 dy$
6.	1	$1.5 \text{ cm}^2/\text{sec}$	6.	4	200m
7.	1	$\frac{9}{4}$	7.	1	1
8.	1	0	8.	4	k^{n-1} (adj I)
9.	3	$\pm 1, \pm i$	9.	1	1
10.	4	(i), (ii), and (iii)	10.	2	$\frac{1}{\sqrt{6}}$
11.	4	200m	11.	3	$\omega^n = 1$
12.	1	1	12.	1	1, 1
13.	4	k^{n-1} (adj I)	13.	2	2π
14.	1	1	14.	4	9π
15.	2	$\frac{1}{\sqrt{6}}$	15.	1	20π
16.	2	$(-8, -6, -22)$	16.	1	$1.5 \text{ cm}^2/\text{sec}$
17.	3	2	17.	1	$\frac{9}{4}$
18.	2	$\sqrt{3}\lambda$	18.	1	0
19.	1	$(2, -1, 4)$ and 5	19.	3	$\pm 1, \pm i$
20.	1	$\pi \int_c^d x^2 dy$	20.	4	(i), (ii), and (iii)
21.	1	(6, 6)	21.	4	$x^2 - y^2 - 2xy = c$
22.	3	$\frac{9}{4}$	22.	1	$\frac{dy}{dx} = \lambda y$
23.	3	4	23.	4	$\int_e Q dx$
24.	1	$\left(-\frac{1}{2}, -8\right)$	24.	2	an asymptote parallel to y-axis
25.	4	$\cos \frac{\pi}{2} - i \sin \frac{\pi}{2}$	25.	1	0
26.	3	$\omega^n = 1$	26.	4	$Q - \{0\}$
27.	1	1, 1	27.	3	3
28.	2	2π	28.	3	$\frac{25}{51}$

29.	4	9π	29.	2	$\frac{24}{169}$
30.	1	20π	30.	2	all possible values between certain given limits
31.	4	$Q - \{0\}$	31.	2	4
32.	3	3	32.	4	inverse axiom
33.	3	$\frac{25}{51}$	33.	3	ω^{n-k}
34.	2	$\frac{24}{169}$	34.	4	taking finite number of elementary transformations
35.	2	all possible values between certain given limits	35.	2	$\frac{1}{50\pi} \text{ cm/min}$
36.	4	$x^2 - y^2 - 2xy = c$	36.	1	(6, 6)
37.	1	$\frac{dy}{dx} = \lambda y$	37.	3	$\frac{9}{4}$
38.	4	$\int_e Q dx$	38.	3	4
39.	2	an asymptote parallel to y-axis	39.	1	$\left(-\frac{1}{2}, -8\right)$
40.	1	0	40.	4	$\cos \frac{\pi}{2} - i \sin \frac{\pi}{2}$

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SECTION – B

41. $AB = \begin{bmatrix} 2 & 3 \\ 1 & 1 \end{bmatrix}$ - 1 mark

$(AB)^{-1} = \begin{bmatrix} -1 & 3 \\ 1 & -2 \end{bmatrix}$ - 1 mark

$B^{-1} = \begin{bmatrix} 2 & 1 \\ -1 & 0 \end{bmatrix}$ - 1 mark

$A^{-1} = \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$ - 1 mark

$B^{-1}A^{-1} = \begin{bmatrix} -1 & 3 \\ 1 & -2 \end{bmatrix}$ - 1 mark

$(AB)^{-1} = B^{-1}A^{-1}$ - 1 mark

42. $\Delta = 0$ - 1 mark

$\Delta x = 0$ - 1 mark

$\Delta y = 0$ - 1 mark

One of the coefficients a_{ij} of $\Delta \neq 0$ - 1 mark

\therefore The solution set is $(x, y) = \left(\frac{9-5K}{4}, K\right), K \in \mathbb{R}$ - 2 marks

43. i) $\vec{a} + \vec{b} + \vec{c} = \vec{0}$ - 1 mark

$(2\vec{i} - \vec{j} + \vec{k}) \cdot (\vec{i} - 3\vec{j} - 5\vec{k}) = 0$ - 1 mark

\therefore angle between two sides is 90° - 1 mark

Note : For any other method, full marks may be given

- ii) $\vec{r} = -\vec{i} - \vec{k}$ - 1 mark
 $\vec{M} = \vec{r} \times \vec{F}$ - 1 mark
 $\vec{M} = 2\vec{i} - 7\vec{j} - 2\vec{k}$ - 1 mark

44. $\vec{a} = 2\vec{i} + 6\vec{j} - 7\vec{k}$ and $\vec{b} = -2\vec{i} + 4\vec{j} - 3\vec{k}$ - 1 mark
 $[\vec{r} - (2\vec{i} + 6\vec{j} - 7\vec{k})][\vec{r} - (-2\vec{i} + 4\vec{j} - 3\vec{k})] = 0$ - 2 marks
 $x^2 + y^2 + z^2 - 10y + 10z + 41 = 0$ - 1 mark
Centre (0, 5, -5) - 1 mark
Radius = 3 - 1 mark

45. $1 + i = \sqrt{2} \left(\cos \frac{\pi}{4} + i \sin \frac{\pi}{4} \right)$ - 3 marks
 $(1 + i)^n = (\sqrt{2})^n \left(\cos \frac{n\pi}{4} + i \sin \frac{n\pi}{4} \right)$ - 1 mark
 $(1 + i)^n = (\sqrt{2})^n \left(\cos \frac{n\pi}{4} - i \sin \frac{n\pi}{4} \right)$ - 1 mark
 $(1 + i)^n + (1 - i)^n = 2^{\frac{n+2}{2}} \cos \frac{n\pi}{4}$ - 1 mark

46. i) $|(a_1 + ib_1)| |(a_2 + ib_2)| \dots |(a_n + ib_n)| = |A + iB|$ - 1 mark
 $\sqrt{a_1^2 + b_1^2} \sqrt{a_2^2 + b_2^2} \dots \sqrt{a_n^2 + b_n^2} = \sqrt{A^2 + B^2}$ - 1 mark
On squaring
 $(a_1^2 + b_1^2)(a_2^2 + b_2^2) \dots (a_n^2 + b_n^2) = A^2 + B^2$ - 1 mark
ii) $\arg(a_1 + ib_1) + \arg(a_2 + ib_2) + \dots + \arg(a_n + ib_n) = \arg(A + iB)$ - 1 mark
 $\tan^{-1} \left(\frac{b_1}{a_1} \right) + \tan^{-1} \left(\frac{b_2}{a_2} \right) + \dots + \tan^{-1} \left(\frac{b_n}{a_n} \right) = \tan^{-1} \left(\frac{B}{A} \right)$ - 1 mark
By taking the general value
 $\tan^{-1} \left(\frac{b_1}{a_1} \right) + \tan^{-1} \left(\frac{b_2}{a_2} \right) + \dots + \tan^{-1} \left(\frac{b_n}{a_n} \right) = k\pi + \tan^{-1} \left(\frac{B}{A} \right)$ - 1 mark

47. Rough diagram - 2 marks
Co-ordinate of A (2ct, 0) - 1 mark
Co-ordinate of B $(0, \frac{2c}{t})$ - 1 mark
The mid-point of AB $(ct, \frac{c}{t})$ - 2 marks

48. $f(0) = 1$ - 1 mark
 $f'(0) = -1$ - 1 mark
 $f''(0) = 2$ - 1 mark
 $\frac{1}{1+x} = 1 - x + x^2 - \dots$ - 3 marks
Note : The sign of the 4th term may be put as '+' or '-'

49. $I = \int_0^3 \frac{\sqrt{x}}{\sqrt{x} + \sqrt{3-x}} dx$ - 1 mark
 $I = \int_0^3 \frac{\sqrt{3-x}}{\sqrt{3-x} + \sqrt{x}} dx$ - 2 marks

$$2I = \int_0^3 dx \quad (\text{or}) \quad [x]_0^3 \quad - 2 \text{ marks}$$

$$I = \frac{3}{2} \quad - 1 \text{ mark}$$

50. $IF = \sin x$ - 2 marks

Solution is $y \sin x = \int \sin 2x dx$ - 2 marks

$$y \sin x = \frac{-\cos 2x}{2} + c \quad (\text{or}) \quad 2y \sin x + \cos 2x = c \quad - 2 \text{ marks}$$

51.

p	q	r	$p \vee q$	$(p \vee q) \wedge r$
T	T	T	T	T
T	T	F	T	F
T	F	T	T	T
T	F	F	T	F
F	T	T	T	T
F	T	F	T	F
F	F	T	F	F
F	F	F	F	F

column 1 to 4 (each 1 mark) - 4 marks

column 5 - 2 marks

Note : (i) Instead of F and T one may use 0 and 1 or 1 and 0
(ii) The order of the rows need not be as in the scheme

52. Stating:

$$a * b = a * c \Rightarrow b = c \quad - 1 \text{ mark}$$

$$b * a = c * a \Rightarrow b = c \quad - 1 \text{ mark}$$

Proving

$$a * b = a * c \Rightarrow b = c \quad - 1 \text{ mark}$$

$$b * a = c * a \Rightarrow b = c \quad - 1 \text{ mark}$$

Note :

(i) For L.C.L the left elements must be same.

(ii) For R.C.L the right elements must be same.

(iii) One may take any three different elements.

53. (i) $\int_{-\infty}^{\infty} f(x) dx = \frac{2}{9} \int_0^3 x dx$ - 1 mark

$$= 1 \quad - 1 \text{ mark}$$

$\therefore f(x)$ is a p.d.f - 1 mark

(ii) $np = 6$, $npq = 9$ - 1 mark

In Binomial distribution mean > variance, Since $np > npq$ ($\because q < 1$) - 1 mark

The given statement is false - 1 mark

54. $f(x) = Ke^{-2(x^2+2x-1)}$ - 1 mark

$$= Ke^{-2(x-1)^2} \quad - 1 \text{ mark}$$

$$= Ke^{-\frac{1}{2}\left(\frac{x-1}{\frac{1}{2}}\right)^2} \quad - 1 \text{ mark}$$

$M = 1$ - 1 mark

$$\sigma = \frac{1}{2} \quad - 1 \text{ mark}$$

$$K = \sqrt{\frac{2}{\pi}} \quad - 1 \text{ mark}$$

55. (a) $m = \frac{dy}{dx} = 2x - 1$ - 1 mark
 At (1, -2), $m = 1$ - 1 mark
 The equations of the tangent $y = x - 3$ - 2 marks
 The equations of the tangent $y = -x - 1$ - 2 marks
 (OR)
 (b) $T = k\sqrt{l}$
 $\log T = \log K + \frac{1}{2} \log l$ - 1 mark
 $\frac{1}{T} dT = \frac{1}{2} \frac{1}{l} dl$ - 1 mark
 $\frac{\Delta T}{T} \times 100 = \frac{1}{2} \times \frac{dl}{l} \times 100$ - 1 mark
 $= \frac{1}{2} \times \frac{10.3}{32.1} \times 100$ - 1 mark
 $= -0.156\%$ - 1 mark
 The percentage error in the time of swing is a decrease of 0.156 - 1 mark

56. $[A, B] = \begin{bmatrix} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 14 \\ 1 & 4 & 7 & 30 \end{bmatrix}$ - 1 mark
 $\sim \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 8 \\ 0 & 3 & 6 & 24 \end{bmatrix} \begin{matrix} R_2 \rightarrow R_2 - R_1; \\ R_3 \rightarrow R_3 - R_1 \end{matrix}$ - 2 marks
 $\sim \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 8 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} R_3 \rightarrow R_3 - 3R_2 \end{matrix}$ - 1 mark
 $\rho(A) = \rho(A, B) = 2 < 3$ (no of unknowns) - 1 mark
 The given system is consistent and has an infinite number of solutions - 1 mark
 Taking $Z = K$ - 1 mark
 $X = K - 2$ - 1 mark
 $y = 8 - 2K$ - 1 mark
 \therefore Solution set is $(x, y, z) = \{K - 2, 8 - 2K, K\}, K \in \mathbb{R}$ - 1 mark

57. Condition for intersecting is

$$[(\vec{a}_2 - \vec{a}_1) \cdot \vec{u} \cdot \vec{v}] = 0 \quad (\text{OR}) \quad \begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ l_1 & m_1 & n_1 \\ l_2 & m_2 & n_2 \end{vmatrix} = 0$$
 - 1 mark

To prove $[(\vec{a}_2 - \vec{a}_1) \cdot \vec{u} \cdot \vec{v}] = 0$ - 2 marks

Take $\frac{x-1}{1} = \frac{y+1}{-1} = \frac{z}{3} = \lambda$ - 1 mark

Point $(\lambda + 1, -\lambda - 1, 3\lambda)$ - 1 mark

Take $\frac{x-2}{1} = \frac{y-1}{2} = \frac{z+1}{-1} = \mu$ - 1 mark

Point $(\mu + 2, 2\mu + 1, -\mu - 1)$ - 1 mark

$(\lambda + 1, -\lambda - 1, 3\lambda) = (\mu + 2, 2\mu + 1, -\mu - 1)$ - 1 mark

$\mu = -1, \lambda = 0$
 The point of intersection is $(1, -1, 0)$

- 1 mark
 - 1 mark

58. $\vec{a} = -\vec{i} + 3\vec{j} + 2\vec{k}$ - 1 mark
 $\vec{u} = \vec{i} + 2\vec{j} + 2\vec{k}$ - 1 mark
 $\vec{v} = 3\vec{i} + \vec{j} + 2\vec{k}$ - 1 mark

Vector Form

$$\vec{r} = (-\vec{i} + 3\vec{j} + 2\vec{k}) + s(\vec{i} + 2\vec{j} + 2\vec{k}) + t(3\vec{i} + \vec{j} + 2\vec{k})$$
 - 2 marks

Cartesian Form

$$\begin{vmatrix} x+1 & y-3 & z-2 \\ 1 & 2 & 2 \\ 3 & 1 & 2 \end{vmatrix} = 0$$
 - 3 marks

$$2x + 4y - 5z = 0$$
 - 2 marks

59. $Z = x + iy$ - 1 mark
 $\frac{Z+1}{Z+i} = \frac{(x+1)+iy}{x+i(y+1)}$ - 2 marks
 $\frac{(x+1)+iy}{x+i(y+1)} \times \frac{x-i(y+1)}{x-i(y+1)}$ - 2 marks
 $\frac{x(x+1)+y(y+1)}{x^2+(y+1)^2} = 1$ - 3 marks
 \therefore Locus of P is $x - y = 1$ - 2 marks

60. $(x - 3)^2 = 12(y + 1)$ - 2 marks
 Axis : $x - 3 = 0$ - 1 mark
 Vertex : $(3, -1)$ - 1 mark
 Focus : $(3, 2)$ - 1 mark
 Directrix : $y + 4 = 0$ - 1 mark
 Latus rectum : 12 - 1 mark
 Equation of Latus rectum : $y - 2 = 0$ - 1 mark
 Rough Diagram - 2 marks

61. Rough diagram - 2 marks
 $A = 36, e = 0.206$
 (i) closest distance $F_1A = CA - CF_1$ - 1 mark
 $= a - ae = a(1 - e)$ - 1 mark
 $= 36 \times 0.794$ - 1 mark
 $= 28.584$ million miles - 1 mark
 (ii) Greatest distance $F_1A^1 = F_1C + CA^1$ - 1 mark
 $= ae + a = a(e + 1)$ - 1 mark
 $= 36 \times 1.206$ - 1 mark
 $= 43.416$ million miles - 1 mark

62. $\lim_{x \rightarrow 0^+} x^{\sin x}$ is of the form 0^0 . - 1 mark
 Let $y = x^{\sin x} \Rightarrow \log y = \sin x \log x$ - 1 mark
 $\log y = \frac{\log x}{\operatorname{cosec} x}$ - 1 mark
 $\lim_{x \rightarrow 0^+} \log y = \lim_{x \rightarrow 0^+} \frac{\log x}{\operatorname{cosec} x} \left(\frac{-\alpha}{\alpha} \text{ form} \right)$ - 1 mark
 $= \lim_{x \rightarrow 0^+} \frac{-\sin^2 x}{x \cos x} (\div \text{ form})$ - 2 marks

$$\lim_{x \rightarrow 0^+} \log y = 0 \quad - 2 \text{ marks}$$

$$\lim_{x \rightarrow 0^+} y = e^0 = 1 \quad - 2 \text{ marks}$$

63. $f'(\theta) = 2 \cos 2\theta$ - 1 mark
 $f''(\theta) = -4 \sin 2\theta$ - 1 mark

$$f'''(\theta) = 0 \Rightarrow \theta = \frac{\pi}{2} \in (0, \pi) \quad - 2 \text{ marks}$$

$(0, \frac{\pi}{2}) \rightarrow$ concave downward (or) convex upward - 2 marks

$(\frac{\pi}{2}, \pi) \rightarrow$ concave upward (or) convex downward - 2 marks

Point of inflection $(\frac{\pi}{2}, 0)$ - 2 marks

64. $\frac{\partial u}{\partial x} = 3 \cos 3x \cos 4y$ - 2 marks

$$\frac{\partial u}{\partial y} = -4 \sin 3x \sin 4y \quad - 2 \text{ marks}$$

$$\frac{\partial^2 u}{\partial x \partial y} = -12 \cos 3x \sin 4y \quad - 2 \text{ marks}$$

$$\frac{\partial^2 u}{\partial y \partial x} = -12 \cos 3x \sin 4y \quad - 2 \text{ marks}$$

$$\frac{\partial^2 u}{\partial x \partial y} = \frac{\partial^2 u}{\partial y \partial x} \quad - 2 \text{ marks}$$

65. Eqn of AB is $y = \frac{3}{2}(x+1)$ - 1 mark

Eqn of Bc is $y = \frac{7-x}{2}$ - 1 mark

Eqn of CB is $y = \frac{1}{2}(x+1)$ - 1 mark

$$\text{Area} = \int_{-1}^1 \frac{3}{2}(x+1)dx + \int_1^3 \left(\frac{7-x}{2}\right)dx - \int_{-1}^3 \left(\frac{x+1}{2}\right)dx \quad - 2 \text{ marks}$$

$$= \frac{3}{2} \left[\frac{x^2}{2} + x \right]_{-1}^1 + \left[7x - \frac{x^2}{2} \right]_1^3 - \frac{1}{2} \left[\frac{x^2}{2} + x \right]_{-1}^3 \quad - 1 \text{ mark}$$

$$= 4 \text{ sq units} \quad - 2 \text{ marks}$$

66. $p^2 - 6p + 9 = 0$ - 1 mark

The CF is $(A + Bx)e^{3x}$ - 2 marks

$$PI_1 = \left(\frac{x}{9} + \frac{2}{27} \right) \quad - 3 \text{ marks}$$

$$PI_2 = e^{2x} \quad - 2 \text{ marks}$$

$$Y = y = (A + Bx)e^{3x} + \left(\frac{x}{9} + \frac{2}{27} \right) + e^{2x} \quad - 2 \text{ marks}$$

Note : (1) Instead of $A + Bx$ one may use $Ax + N$

(2) Instead of A, B one may use any other different symbols

67. $\frac{dt}{dt} \alpha(T - 15)$ - 1 mark

$\frac{dt}{dt} = K(T - 15)$		- 1 mark
$T - 15 = ce^{Kt}$		- 2 marks
$C = 85$		- 1 mark
$e^{5k} = \frac{45}{85}$		- 2 marks
When $t = 10$, $T = 15 + 85e^{10K}$		- 2 marks
$T = 38.82C^\circ$		- 1 mark

68.	Closure axiom	Heading	- 1 mark
	Explanation		- 1 mark
	Associative axiom	Heading	- 1 mark
	Explanation		- 1 mark
	Identity axiom	Heading	- 1 mark
	[0] is the identity element		- 1 mark
	Inverse axiom	Heading	- 1 mark
	Inverse of $a + b\sqrt{2}$ is $-a - b\sqrt{2}$		- 1 mark
	Explanation		- 1 mark

69.	(i) $\lambda = 4.5$		- 1 mark
	$P(x = 9) = \frac{e^{-4.5} \times (4.5)^9}{\angle 9}$		- 2 marks
	(ii) $\lambda = 7.2$		- 1 mark
	$P(x < 10) = \sum_{x=0}^9 \frac{e^{-7.2} \times (7.2)^x}{\angle x}$		- 2 marks
	(iii) $\lambda = 9.9$		- 1 mark
	$P(x \geq 14) = 1 - p(X < 14)$		- 1 mark
	$1 - \sum_0^{13} \frac{e^{-9.9} \times (9.9)^x}{\angle x}$		- 2 marks

70.	a) The condition for $y = mx + c$ to be a tangent of ellipse is $c^2 = a^2m^2 + b^2$		- 2 marks
	$m = 1$		- 1 mark
	$c = 4$		- 1 mark
	$a^2 = 9, a^2m^2 + b^2 = 16$		- 2 marks
	It touches to the ellipse		
	The point of contact is $\left(\frac{-a^2m}{c}, \frac{b^2}{c}\right)$		- 1 mark
	i.e. (-3, 1)		- 2 marks

b) Rough Diagram		- 1 mark
$\frac{dx}{dt} = -3a \cos^2 t \sin t$		- 2 marks
$\frac{dy}{dt} = 3a \sin^2 t \cos t$		- 2 marks
$\sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} = 3a \sin t \cos t$		- 2 marks
Length = $4 \int_0^{\frac{\pi}{2}} 3a \sin t \cos t dt$		- 2 marks
= 6a	www.mathstimes.com	- 1 mark